

GLOBAL ATTRACTOR FOR A KLEIN-GORDON-SCHRÖDINGER TYPE SYSTEM

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ABSTRACT. In this paper we prove the existence and uniqueness of solutions for the following evolution system of Klein-Gordon-Schrödinger type

$$\begin{aligned}i\psi_t + \kappa\psi_{xx} + i\alpha\psi &= \phi\psi + f(x), \\ \phi_{tt} - \phi_{xx} + \phi + \lambda\phi_t &= -Re\psi_x + g(x), \\ \psi(x, 0) = \psi_0(x), \phi(x, 0) &= \phi_0(x), \phi_t(x, 0) = \phi_1(x), \\ \psi(x, t) = \phi(x, t) = 0, & \quad x \in \partial\Omega, \quad t > 0,\end{aligned}$$

where $x \in \Omega$, $t > 0$, $\kappa > 0$, $\alpha > 0$, $\lambda > 0$, $f(x)$ and $g(x)$ are the driving terms and Ω (bounded) $\subset \mathbf{R}$. Also we prove the continuous dependence of solutions of the system on the initial data as well as the existence of a global attractor.

1. Introduction. The aim of this paper is to prove the existence of a global attractor for the following Klein-Gordon-Schrödinger type system defined in a bounded interval $\Omega \subset \mathbf{R}$

$$i\psi_t + \kappa\psi_{xx} + i\alpha\psi = \phi\psi + f(x), \quad x \in \Omega, \quad t > 0, \quad (1)$$

$$\phi_{tt} - \phi_{xx} + \phi + \lambda\phi_t = -Re\psi_x + g(x), \quad x \in \Omega, \quad t > 0, \quad (2)$$

$$\psi(x, 0) = \psi_0(x), \quad \phi(x, 0) = \phi_0(x), \quad \phi_t(x, 0) = \phi_1(x), \quad x \in \Omega, \quad t > 0, \quad (3)$$

$$\psi(x, t) = \phi(x, t) = 0, \quad x \in \partial\Omega, \quad t > 0, \quad \kappa > 0, \quad \alpha > 0, \quad \lambda > 0, \quad (4)$$

where $f(x), g(x)$ are the driving terms. Systems of Klein-Gordon-Schrödinger type have been studied for many years. To our knowledge, it seems that the first problems of this type is the so called *Yukawa System* [11], which goes back to 1935 (see, [2] and the references therein). An other model which is of the same type is the so called *Zakharov System*, which is formed by V. E. Zakharov [13] in early seventies (see, [3] and [4] and the references therein).

Here we consider a *Klein-Gordon-Schrödinger system of a third type*, which is the problem (1) - (4). This problem is the outcome of a modeling process, described in all details in a work by N. Karachalios, N. Stavrakakis and P. Xanthopoulos [6]. Problem (1) - (4) models the *Upper Hybrid Heating* (UHH) scheme for plasmas in fusion devices. (UHH) is the dominant branch of the general *Electron Cyclotron Resonance Heating* (ECRH) scheme, which, for Tokamaks and Stellarators, constitutes a basic method of plasma build-up and heating. The celebrated Zakharov system, is highly successful in a multitude of applications. However, regarding the study of (UHH) Zakharov system cannot not be implemented for certain reasons.

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The variable ψ stands for the dimensionless low frequency electron field, whereas the (real) variable ϕ denotes the dimensionless low frequency density. For more details on the physical interpretation and the modeling process of the system the reader may refer to [6], [12] and the references therein.

In this paper we prove the existence of a global attractor in the space $(H_0^1(\Omega) \cap H^2(\Omega))^2 \times H_0^1(\Omega)$ which attracts all bounded sets of $(H_0^1(\Omega) \cap H^2(\Omega))^2 \times H_0^1(\Omega)$ in the norm topology. This paper is divided in four Sections. In the Second Section, we derive some useful estimates on the solutions of the system (1) - (4) in $(H_0^1(\Omega) \cap H^2(\Omega))^2 \times H_0^1(\Omega)$. The Third Section, is based on an energy method first introduced by J. Ball [1]. We are going to use the energy equations of the problem to prove the continuity of solutions on the initial data in the space $(H_0^1(\Omega) \cap H^2(\Omega))^2 \times H_0^1(\Omega)$. In Section 4, we show the asymptotic compactness of the dynamical system and the existence of a global attractor. In a recent joint work we study the finite dimensionality of the global attractor (see, [10]).

Notation: Denote by H^s both the standard real and complex Sobolev spaces. For simplicity reasons sometimes we use H^s , L^s for $H^s(\Omega)$, $L^s(\Omega)$ and $\|\cdot\|$, (\cdot, \cdot) for the norm and the inner product of $L^2(\Omega)$, respectively. $\int dx$ denotes the integration over Ω . Finally, C is a general symbol for any positive constant.

2. Global Existence. In this section we derive a priori estimates for the solutions of the Klein-Gordon-Schrödinger system. Let us introduce the transformation $\theta = \phi_t + \delta\phi$, where θ is real, with δ a small positive constant to be specified later. Then, system (1) - (4) takes the form

$$i\psi_t + \kappa\psi_{xx} + i\alpha\psi = \phi\psi + f, \quad x \in \Omega, \quad t > 0, \quad (5)$$

$$\phi_t + \delta\phi = \theta, \quad x \in \Omega, \quad t > 0, \quad (6)$$

$$\theta_t + (\lambda - \delta)\theta - \phi_{xx} + (1 - \delta(\lambda - \delta))\phi = -Re\psi_x + g, \quad x \in \Omega, \quad t > 0, \quad (7)$$

Also the initial and boundary conditions take the form

$$\psi(x, 0) = \psi_0(x), \quad \phi(x, 0) = \phi_0(x), \quad \theta(x, 0) = \theta_0(x), \quad x \in \Omega \quad (8)$$

$$\psi(x, t) = \phi(x, t) = 0, \quad x \in \partial\Omega, \quad t > 0. \quad (9)$$

Lemma 1. *Let $\|\psi_0(t)\| \leq R$, for some $R > 0$ and $f \in L^2(\Omega)$. Every solution of (5)-(9) satisfies*

$$\|\psi(t)\| \leq R^*, \quad t \geq t_1,$$

where R^* is a constant depending on α , $\|f\|$; t_1 depending on α , $\|f\|$ and R .

Proof The proof is analogue to the one of Lemma 2.1 in [9]. \triangleleft

Lemma 2. *Assume that $f, g \in L^2(\Omega)$ and $\|(\psi_0, \phi_0, \theta_0)\|_{H_0^1 \times H_0^1 \times L^2} \leq R$, where $R > 0$. Then, there exists a constant δ_1 such that when $\delta \leq \delta_1$, every solution (ψ, ϕ, θ) of problem (5)-(9) satisfies*

$$\|\psi(t)\|_{H_0^1} + \|\phi(t)\|_{H_0^1} + \|\theta(t)\| \leq M_1, \quad t \geq t_2,$$

where M_1 depends on $\alpha, \kappa, \lambda, \delta_1, \|f\|, \|g\|$ and t_2 on $\alpha, \kappa, \lambda, \delta_1, \|f\|, \|g\|$ and R .

Proof. Multiplying equation (5) by $-\psi_t$, integrating and taking the real part gives

$$\begin{aligned} \frac{1}{2} \frac{d}{dt} \left(\kappa \|\psi_x\|^2 + \int \phi |\psi|^2 + 2Re \int f \bar{\psi} \right) + \kappa \alpha \|\psi_x\|^2 + \left(\alpha + \frac{\delta}{2} \right) \int \phi |\psi|^2 \\ = \frac{1}{2} \int \theta |\psi|^2 + \alpha Re \int f \bar{\psi}. \end{aligned} \quad (10)$$

Next, multiplying equation (7) by θ and substituting θ from equation (6) implies

$$\begin{aligned} \frac{1}{2} \frac{d}{dt} (\|\theta\|^2 + \|\phi_x\|^2 + (1 - \delta(\lambda - \delta))\|\phi\|^2) + (\lambda - \delta)\|\theta\|^2 + \delta\|\phi_x\|^2 \\ + \delta(1 - \delta(\lambda - \delta))\|\phi\|^2 = -Re \int \theta \psi_x + \int g\theta. \end{aligned} \quad (11)$$

Adding relations $2 \times (10)$ and $2 \times (11)$ gives

$$F_1'(t) + \delta F_1(t) = G_1(t), \quad (12)$$

where for simplification reasons the following quantities are introduced

$$F_1 := \kappa \|\psi_x\|^2 + \int \phi |\psi|^2 dx + \|\theta\|^2 + \|\phi_x\|^2 + (1 - \delta(\lambda - \delta))\|\phi\|^2 + 2Re \int f \bar{\psi},$$

$$\begin{aligned} G_1 := & (\delta - 2\kappa\alpha)\|\psi_x\|^2 - 2\alpha \int \phi |\psi|^2 + (3\delta - 2\lambda)\|\theta\|^2 - \delta(1 - \delta(\lambda - \delta))\|\phi\|^2 \\ & - \delta\|\phi_x\|^2 + \int \theta |\psi|^2 + 2(\delta - \alpha)Re \int f \bar{\psi} - 2Re \int \theta \psi_x + 2 \int g\theta. \end{aligned}$$

Taking δ small enough such that $\delta - 2\kappa\alpha < 0$, $3\delta - 2\lambda < 0$, $1 - \delta(\lambda - \delta) > 0$, one can render several terms of G_1 negative. Let us proceed by majorizing the integrals of G_1 as follows

$$\left| \int \theta |\psi|^2 \right| \leq \|\theta\| \|\psi\|_4^2 \leq \|\theta\| \|\psi\|^{1/2} \|\psi\|^{3/2} \leq \frac{\epsilon_1}{2} \|\theta\|^2 + \frac{\epsilon_2}{2} \|\psi_x\|^2 + C,$$

$$\left| 2\alpha \int \phi |\psi|^2 \right| \leq \epsilon_3 \|\phi\|^2 + \frac{\epsilon_2}{2} \|\psi_x\|^2 + C,$$

$$\text{and } \left| \int \theta \psi_x \right| \leq \|\psi_x\| \|\theta\| \leq \frac{\epsilon}{2} \|\psi_x\|^2 + \frac{1}{2\epsilon} \|\theta\|^2,$$

$$\left| 2(\delta - \alpha) \int f \bar{\psi} \right| \leq C \|f\| \|\psi\| \leq C, \text{ and } \left| 2 \int g\theta \right| \leq 2 \|g\| \|\theta\| \leq \frac{\epsilon_1}{2} \|\theta\|^2 + C.$$

The next step is to estimate the arbitrary positive constants ϵ_1 , ϵ_2 , ϵ , such that the following two inequalities hold simultaneously true $\epsilon_1 + \frac{1}{2\epsilon} \leq -(3\delta - 2\lambda)$, $\epsilon_2 + \frac{\epsilon}{2} \leq -(\delta - 2\kappa\alpha)$. Let $\nu > 0$, $\nu \neq \frac{1}{2}$, $\bar{\alpha} = -(3\delta - 2\lambda)$ and $\bar{\beta} = -(\delta - 2\kappa\alpha)$. Setting $\epsilon_1 = \frac{\bar{\alpha}}{2\nu}$, $\epsilon_2 = \frac{\bar{\beta}}{2\nu}$ we have the following necessary condition: $\bar{\alpha}\bar{\beta} \geq \frac{\nu^2}{(2\nu - 1)^2}$. Since $\bar{\alpha}, \bar{\beta} > 0$ the inequality is always true for sufficiently small ν . Finally, taking ϵ_3 small enough, so that $\epsilon_3 < -\delta(1 - \delta(\lambda - \delta))$ implies

$$F_1'(t) + \delta F_1(t) \leq C.$$

The application of Gronwall's Inequality completes the proof. \square

Lemma 3. *Assume that $f, g \in H_0^1(\Omega)$ and $\|(\psi_0, \phi_0, \theta_0)\|_{(H_0^1 \cap H^2)^2 \times H_0^1} \leq R$, where $R > 0$. Then, there exists a constant δ_1 such that when $\delta \leq \delta_1$, every solution (ψ, ϕ, θ) of the problem (5)-(9) satisfies*

$$\|\psi(t)\|_{H_0^1 \cap H^2} + \|\phi(t)\|_{H_0^1 \cap H^2} + \|\theta(t)\|_{H_0^1} \leq M_2, \quad t \geq t_3,$$

where M depends on $\alpha, \kappa, \lambda, \delta_1, \|f\|_{H_0^1}, \|g\|_{H_0^1}$; and t_3 on $\alpha, \kappa, \lambda, \delta_1, \|f\|_{H_0^1}, \|g\|_{H_0^1}, R$.

Proof. Multiplying relation (5) by $\psi_{xx,t} + \alpha\psi_{xx}$ and taking the real part, produces

$$\begin{aligned} & \frac{1}{2} \frac{d}{dt} \left(\kappa \|\psi_{xx}\|^2 - 2\operatorname{Re} \int \phi\psi\bar{\psi}_{xx} + 2\operatorname{Re} \int f_x\bar{\psi}_x \right) + \kappa\alpha\|\psi_{xx}\|^2 \\ & - (2\alpha + \delta)\operatorname{Re} \int \phi\psi\bar{\psi}_{xx} = -\operatorname{Re} \int \theta\psi\bar{\psi}_{xx} dx - \operatorname{Im} \int \phi^2\psi\bar{\psi}_{xx} - \alpha\operatorname{Re} \int f_x\bar{\psi}_x. \end{aligned} \quad (13)$$

Next, multiplication of equation (7) by $-\theta_{xx}$ and integration gives

$$\begin{aligned} & \frac{1}{2} \frac{d}{dt} \left(\|\theta_x\|^2 + \|\phi_{xx}\|^2 + (1 - \delta(\lambda - \delta))\|\phi_x\|^2 \right) + (\lambda - \delta)\|\theta_x\|^2 \\ & + \delta\|\phi_{xx}\|^2 + \delta(1 - \delta(\lambda - \delta))\|\phi_x\|^2 = -\operatorname{Re} \int \theta_x\psi_{xx} + \int g_x\theta_x. \end{aligned} \quad (14)$$

Furthermore, the addition of equations $2 \times (13)$ and $2 \times (14)$ implies,

$$F_2'(t) + \delta F_2(t) = G_2(t), \quad t \geq t_3,$$

where for simplification reasons the following notation is introduced

$$\begin{aligned} F_2 &:= \kappa\|\psi_{xx}\|^2 - 2\operatorname{Re} \int \phi\psi\bar{\psi}_{xx} + 2\operatorname{Re} \int f_x\bar{\psi}_x + \|\theta_x\|^2 + \|\phi_{xx}\|^2 \\ &+ (1 - \delta(\lambda - \delta))\|\phi_x\|^2, \\ G_2 &:= (\delta - 2\kappa\alpha)\|\psi_{xx}\|^2 + (3\delta - 2\lambda)\|\theta_x\|^2 - \delta\|\phi_{xx}\|^2 - \delta(1 - \delta(\lambda - \delta))\|\phi_x\|^2 \\ &+ 4\alpha\operatorname{Re} \int \phi\psi\bar{\psi}_{xx} - 2\operatorname{Re} \int \theta_x\psi_{xx} - 2\operatorname{Re} \int \theta\psi\bar{\psi}_{xx} dx - 2\operatorname{Im} \int \phi^2\psi\bar{\psi}_{xx} \\ &+ 2(\delta - \alpha) \int f_x\bar{\psi}_x + 2 \int g_x\theta_x. \end{aligned}$$

Taking δ small enough one can render several terms of G_2 negative. Following the same procedure as the one used for the first estimate we can deduce that,

$$F_2'(t) + \delta F_2(t) \leq C, \quad t \geq t_3,$$

therefore by applying Gronwall's Inequality the proof is completed. \triangleleft

Repeating a similar procedure to the one used in the preceding Lemmas we obtain the following results on a finite time interval.

Lemma 4. *Assume that $f, g \in L^2(\Omega)$. Let $\|\psi_0, \phi_0, \theta_0\|_{H_0^1 \times H_0^1 \times L^2} \leq R$, where $R > 0$. Then, there exists a constant δ_1 such that when $\delta \leq \delta_1$, every solution (ψ, ϕ, θ) of the problem (5)-(9) satisfies*

$$\|\psi(t)\|_{H_0^1} + \|\phi(t)\|_{H_0^1} + \|\theta\| \leq L_1, \quad 0 \leq t \leq T,$$

where L_1 depends on $\alpha, \kappa, \lambda, \delta, \|f\|, \|g\|$ and T .

Lemma 5. *Assume that $f, g \in H_0^1(\Omega)$. Let $\|\psi_0, \phi_0, \theta_0\|_{(H_0^1 \cap H^2)^2 \times H_0^1} \leq R$, where $R > 0$. Then, there exists a constant δ_1 such that when $\delta \leq \delta_1$, every solution (ψ, ϕ, θ) of the problem (5)-(9) satisfies*

$$\|\psi(t)\|_{H_0^1 \cap H^2} + \|\phi(t)\|_{H_0^1 \cap H^2} + \|\theta\|_{H_0^1} \leq L_2, \quad 0 \leq t \leq T,$$

where L_2 depends on $\alpha, \kappa, \lambda, \delta, \|f\|_{H_0^1}, \|g\|_{H_0^1}$ and T .

Therefore we are ready to state the main result of this section.

Theorem 1. *Assume that $f, g \in H_0^1(\Omega)$. Let $\|\psi_0, \phi_0, \theta_0\|_{(H_0^1 \cap H^2)^2 \times H_0^1} \leq R$, where $R > 0$. Then, there exists a constant δ_1 such that when $\delta \leq \delta_1$, the system (5) - (9) admits a unique solution satisfying*

$$\begin{aligned} \psi &\in L^\infty(0, \infty; H_0^1(\Omega) \cap H^2(\Omega)), \quad \psi_t \in L^\infty(0, \infty; L^2(\Omega)), \\ \phi &\in L^\infty(0, \infty; H_0^1(\Omega) \cap H^2(\Omega)), \quad \phi_t \in L^\infty(0, \infty; H_0^1(\Omega)), \quad \phi_{tt} \in L^\infty(0, \infty; L^2(\Omega)), \\ \psi(x, 0) &= \psi_0(x), \quad \phi(x, 0) = \phi_0(x), \quad \phi_t(x, 0) = \phi_1(x), \quad x \in \Omega. \end{aligned}$$

Proof. The proof follows the lines of Theorem 3.1 in [6]. \square

3. The Solution Semigroup. Problem (5)-(9) defines a **semigroup** $S(t)$,

$$S(t) : (H_0^1 \cap H^2)^2 \times H_0^1 \rightarrow (H_0^1 \cap H^2)^2 \times H_0^1 \quad (\text{Theorem 1})$$

Let B_1, B_2 denote the following balls of center zero and radius M_1, M_2 respectively

$$\begin{aligned} B_1 &= \{(\psi, \phi, \theta) \in H_0^1 \times H_0^1 \times L^2 : \|\psi\|_{H_0^1} + \|\phi\|_{H_0^1} + \|\theta\| \leq M_1\}, \\ B_2 &= \{(\psi, \phi, \theta) \in (H_0^1 \cap H^2)^2 \times H_0^1 : \|\psi\|_{H_0^1 \cap H^2} + \|\phi\|_{H_0^1 \cap H^2} + \|\theta\|_{H_0^1} \leq M_2\}, \end{aligned} \quad (15)$$

where M_1, M_2 are the constants introduced in Lemmas 2, 3. Therefore, B_1, B_2 are bounded absorbing sets for (5)-(9). Since B_1 is bounded, we see that there exists a constant $T(B_1)$ depending on B_1 such that $S(t)B_1 \subset B_1$, for all $t \geq T(B_1)$.

Lemma 6. *If $(\psi_n, \phi_n, \theta_n) \rightharpoonup (\psi, \phi, \theta)$ weakly in $H_0^1(\Omega) \times H_0^1(\Omega) \times L^2(\Omega)$, then for every $T > 0$, we have*

$$S(\cdot)(\psi_n, \phi_n, \theta_n) \rightharpoonup S(\cdot)(\psi, \phi, \theta), \quad \text{weakly in } L^2(0, T; H_0^1 \times H_0^1 \times L^2), \quad (16)$$

$$S(t)(\psi_n, \phi_n, \theta_n) \rightharpoonup S(t)(\psi, \phi, \theta), \quad \text{weakly in } H_0^1 \times H_0^1 \times L^2, \quad 0 \leq t \leq T. \quad (17)$$

Proof. From the weak convergence and Lemma 4 it follows that $\{S(t)(\psi_n, \phi_n, \theta_n)\}$ is bounded in $L^\infty(0, T; H_0^1 \times H_0^1 \times L^2)$ with

$$\begin{aligned} \left\{ \frac{\partial}{\partial t} S(t) \psi_n \right\}, \left\{ \frac{\partial}{\partial t} S(t) \theta_n \right\} &\text{ bounded in } L^\infty(0, T; H^{-1}), \\ \left\{ \frac{\partial}{\partial t} S(t) \phi_n \right\} &\text{ bounded in } L^\infty(0, T; L^2). \end{aligned}$$

Therefore, exist a subsequence $\{(\psi_{n_j}, \phi_{n_j}, \theta_{n_j})\}$ of $\{(\psi_n, \phi_n, \theta_n)\}$ and $(\psi_\infty, \phi_\infty, \theta_\infty) \in L^\infty(0, T; H_0^1 \times H_0^1 \times L^2)$ such that

$$S(t)(\psi_{n_j}, \phi_{n_j}, \theta_{n_j}) \rightharpoonup (\psi_\infty, \phi_\infty, \theta_\infty), \quad \text{weakly in } L^2(0, T; H_0^1 \times H_0^1 \times L^2), \quad (18)$$

$$\frac{\partial}{\partial t} S(t) \psi_{n_j} \rightharpoonup \frac{\partial}{\partial t} \psi_\infty \quad \text{and} \quad \frac{\partial}{\partial t} S(t) \theta_{n_j} \rightharpoonup \frac{\partial}{\partial t} \theta_\infty, \quad \text{weakly in } L^2(0, T; H^{-1}), \quad (19)$$

$$\frac{\partial}{\partial t} S(t) \phi_{n_j} \rightharpoonup \frac{\partial}{\partial t} \phi_\infty, \quad \text{weakly in } L^2(0, T; L^2). \quad (20)$$

Then, it can be shown that $(\psi_\infty, \phi_\infty, \theta_\infty)$ is a solution of the system (5)-(9) with initial conditions $(\psi_\infty(0), \phi_\infty(0), \theta_\infty(0)) = (\psi, \phi, \theta)$. But in Theorem 1 we established the uniqueness of solutions, that implies $(\psi_\infty, \phi_\infty, \theta_\infty) = S(t)(\psi, \phi, \theta)$ which together with (18) concludes the proof of (16).

Now for equation (17), let us choose $t \in [0, T]$ fixed. From the weak convergence and Lemma 4 $\{S(t)(\psi_n, \phi_n, \theta_n)\}$ is bounded in $H_0^1 \times H_0^1 \times L^2$. So there exists a subsequence $\{(\psi_{n_{j,t}}, \phi_{n_{j,t}}, \theta_{n_{j,t}})\}$ of $\{(\psi_n, \phi_n, \theta_n)\}$ such that $S(t)(\psi_{n_{j,t}}, \phi_{n_{j,t}}, \theta_{n_{j,t}}) \rightharpoonup (\psi_t, \phi_t, \theta_t)$ weakly in $H_0^1 \times H_0^1 \times L^2$, with $(\psi_t, \phi_t, \theta_t) \in H_0^1 \times H_0^1 \times L^2$, where $(\psi_{n_{j,t}}, \phi_{n_{j,t}}, \theta_{n_{j,t}})$ and $(\psi_t, \phi_t, \theta_t)$ both depend on t . By (18)-(20) we can see that

$(\psi_\infty, \phi_\infty, \theta_\infty)$ is a solution of the system with $(\psi_\infty(0), \phi_\infty(0), \theta_\infty(0)) = (\psi, \phi, \theta)$ as well as $(\psi_\infty(t), \phi_\infty(t), \theta_\infty(t)) = (\psi_t, \phi_t, \theta_t)$. Therefore, by the uniqueness of the solution we have $(\psi_t, \phi_t, \theta_t) = (\psi_\infty(t), \phi_\infty(t), \theta_\infty(t)) = S(t)(\psi, \phi, \theta)$. Hence we have proved that any sequence $S(t)(\psi_n, \phi_n, \theta_n)$ has a weakly convergent subsequence that will converge to the same limit $S(t)(\psi, \phi, \theta)$. Therefore by contradiction arguments we conclude that relation (17) holds. \triangleleft

Theorem 2. *Assume that $f, g \in L^2(\Omega)$. The solutions $(\psi, \phi, \theta) \in C(\mathbb{R}^+, H_0^1 \times H_0^1 \times L^2)$ of the problem (5)-(9) depend continuously on the initial data in $H_0^1 \times H_0^1 \times L^2$.*

Proof. Assume that $(\psi_{0,n}, \phi_{0,n}, \theta_{0,n}) \rightarrow (\psi_0, \phi_0, \theta_0)$ in $H_0^1 \times H_0^1 \times L^2$, therefore we need to prove that $S(t)(\psi_n, \phi_n, \theta_n) \rightarrow S(t)(\psi, \phi, \theta), \forall t > 0$, as $n \rightarrow \infty$. Given $t > 0$, we choose $T > t$. From the statement above we know that $\{(\psi_{0,n}, \phi_{0,n}, \theta_{0,n})\}$ is bounded and therefore by Lemma 4 there exists a solution such that

$$\|\psi_n(\tau)\|_{H_0^1} + \|\phi_n(\tau)\|_{H_0^1} + \|\theta_n(\tau)\| \leq C, \quad 0 \leq \tau \leq T, \quad (21)$$

will hold where $(\psi_n(\tau), \phi_n(\tau), \theta_n(\tau)) = S(\tau)(\psi_{0,n}, \phi_{0,n}, \theta_{0,n})$. But from the system (5)-(9) we can see that $\left\| \frac{\partial}{\partial \tau} \psi_n \right\|_{L^2(0,T;H_0^{-1})} + \left\| \frac{\partial}{\partial \tau} \phi_n \right\|_{L^2(0,T;L^2)} \leq C$. Hence, there exists a $(\psi(\tau), \phi(\tau), \theta(\tau)) \in L^\infty(0, T; H_0^1 \times H_0^1 \times L^2)$, such that

$$\begin{aligned} (\psi_n(\tau), \phi_n(\tau), \theta_n(\tau)) &\rightharpoonup (\psi(\tau), \phi(\tau), \theta(\tau)), \text{ weakly in } L^2(0, T; H_0^1 \times H_0^1 \times L^2), \\ \frac{\partial}{\partial \tau} \psi_n &\rightharpoonup \frac{\partial}{\partial \tau} \psi, \text{ weakly in } L^2(0, T; H_0^{-1}), \quad \frac{\partial}{\partial \tau} \phi_n \rightharpoonup \frac{\partial}{\partial \tau} \phi, \text{ weakly in } L^2(0, T; L^2). \end{aligned} \quad (22)$$

Thereby, using the relations above and standard compactness results we have

$$(\psi_n, \phi_n) \rightarrow (\psi, \phi) \text{ strongly in } L^2(0, T; L^2 \times L^2). \quad (23)$$

Using similar arguments as the ones above and equation (21) we can deduce with the help of Lemma 2 that for a fixed t there exists a $(\psi(t), \phi(t), \theta(t))$ such that

$$(\psi_n(t), \phi_n(t), \theta_n(t)) \rightharpoonup (\psi(t), \phi(t), \theta(t)) \text{ weakly in } H_0^1 \times H_0^1 \times L^2,$$

where $(\psi(t), \phi(t), \theta(t))$ is the solution of the problem (5)-(9) with initial conditions $(\psi_0, \phi_0, \theta_0)$. Taking into consideration Lemma 6, the arguments above imply that

$$S(t)(\psi_n, \phi_n, \theta_n) \rightharpoonup S(t)(\psi, \phi, \theta) \text{ weakly in } H_0^1 \times H_0^1 \times L^2. \quad (24)$$

To prove the strong convergence for the above sequence the energy equation (12) is used. Every solution of the system (5)-(9) verifies the energy equation, hence

$$F_1(S(t)(\psi_0, \phi_0, \theta_0)) = e^{-\delta t} F_1(\psi_0, \phi_0, \theta_0) + \int_0^t e^{-\delta(t-\tau)} G_1(S(t)(\psi_0, \phi_0, \theta_0)) d\tau, \quad (25)$$

where $(\psi(t), \phi(t), \theta(t)) = S(t)(\psi_0, \phi_0, \theta_0)$. The same will also hold for the solution $S(t)(\psi_{0,n}, \phi_{0,n}, \theta_{0,n})$, i.e.,

$$\begin{aligned} F_1(S(t)(\psi_{0,n}, \phi_{0,n}, \theta_{0,n})) &= e^{-\delta t} F_1(\psi_{0,n}, \phi_{0,n}, \theta_{0,n}) \\ &+ \int_0^t e^{-\delta(t-\tau)} G_1(S(t)(\psi_{0,n}, \phi_{0,n}, \theta_{0,n})) d\tau. \end{aligned} \quad (26)$$

From our assumption that $(\psi_{0,n}, \phi_{0,n}, \theta_{0,n}) \rightarrow (\psi_0, \phi_0, \theta_0)$ strongly in $H_0^1 \times H_0^1 \times L^2$, and the definition of F_1 we can deduce that $F_1(\psi_{0,n}, \phi_{0,n}, \theta_{0,n}) \rightarrow F_1(\psi_0, \phi_0, \theta_0)$,

as $n \rightarrow \infty$. Now rewriting the last term of (26) as

$$\begin{aligned}
 & \int_0^t e^{-\delta(t-\tau)} G_1(S(t)(\psi_{0,n}, \phi_{0,n}, \theta_{0,n})) d\tau \\
 = & \int_0^t e^{-\delta(t-\tau)} \left((\delta - 2k\alpha) \|S(t)\psi_{0x,n}\|^2 - 2\alpha \int S(t)\phi_{0,n} |S(t)\psi_{0,n}|^2 \right) \\
 & + \int_0^t e^{-\delta(t-\tau)} \left((3\delta - 2\lambda) \|S(t)\theta_{0,n}\|^2 - \delta(1 - \delta(\lambda - \delta)) \|S(t)\phi_{0,n}\|^2 - \delta \|S(t)\phi_{0x,n}\|^2 \right) \\
 & + \int_0^t e^{-\delta(t-\tau)} \left(\int S(t)\theta_{0,n} |S(t)\psi_{0,n}|^2 - 2Re \int S(t)\theta_{0,n} S(t)\psi_{0x,n} \right) \\
 & + \int_0^t e^{-\delta(t-\tau)} \left(2(\delta - \alpha) Re \int f \overline{S(t)\psi_{0,n}} + 2 \int g S(t)\theta_{0,n} \right). \tag{27}
 \end{aligned}$$

By the weak convergence of relation (22) we have that

$$\liminf_{n \rightarrow \infty} \|e^{-\delta(t-\tau)} S(\tau)\psi_{0,n}\|_{L^2(0,t;H_0^1)} \geq \|e^{-\delta(t-\tau)} S(t)\psi_0\|_{L^2(0,t;H_0^1)}, \tag{28}$$

$$\liminf_{n \rightarrow \infty} \|e^{-\delta(t-\tau)} S(\tau)\phi_{0,n}\|_{L^2(0,t;H_0^1)} \geq \|e^{-\delta(t-\tau)} S(t)\phi_0\|_{L^2(0,t;H_0^1)}, \tag{29}$$

$$\liminf_{n \rightarrow \infty} \|e^{-\delta(t-\tau)} S(\tau)\theta_{0,n}\|_{L^2(0,t;L^2)} \geq \|e^{-\delta(t-\tau)} S(t)\theta_0\|_{L^2(0,t;L^2)}. \tag{30}$$

Then by choosing δ small enough so that $(2k\alpha - \delta) > 0$, $(2\lambda - 3\delta) > 0$, $\delta(1 - \delta(\lambda - \delta)) > 0$, the first terms of relation (27) may be rewritten as

$$\begin{aligned}
 & \limsup_{n \rightarrow \infty} - \int_0^t e^{-\delta(t-\tau)} \left((2k\alpha - \delta) \|S(t)\psi_{0x,n}\|^2 + (2\lambda - 3\delta) \|S(t)\theta_{0,n}\|^2 \right. \\
 & \quad \left. + \delta(1 - \delta(\lambda - \delta)) \|S(t)\phi_{0,n}\|^2 - \delta \|S(t)\phi_{0x,n}\|^2 \right) \\
 & \leq - \int_0^t e^{-\delta(t-\tau)} \left((2k\alpha - \delta) \|S(t)\psi_{0x}\|^2 + (2\lambda - 3\delta) \|S(t)\theta_0\|^2 \right. \\
 & \quad \left. + \delta(1 - \delta(\lambda - \delta)) \|S(t)\phi_0\|^2 - \delta \|S(t)\phi_{0x}\|^2 \right). \tag{31}
 \end{aligned}$$

Next,

$$\begin{aligned}
 & \left| \int_0^t e^{-\delta(t-\tau)} \int S(t)\phi_{0,n} |S(t)\psi_{0,n}|^2 - \int_0^t e^{-\delta(t-\tau)} \int S(t)\phi_0 |S(t)\psi_0|^2 \right| \\
 & \leq \int_0^t e^{-\delta(t-\tau)} \|S(t)\phi_{0,n} - S(t)\phi_0\| \|S(t)\psi_n\|_4^2 \\
 & \quad + \int_0^t e^{-\delta(t-\tau)} \|S(t)\phi_0\|_3 \|S(t)\psi_{0,n} - S(t)\psi_0\| (\|S(t)\psi_{0,n}\|_6 + \|S(t)\psi_0\|_6).
 \end{aligned}$$

Using the Sobolev Embedding Theorem and Lemma 4, produces

$$\begin{aligned}
 & \|S(t)\psi_{0,n}\|_{L^\infty(0,t;H_0^1)}^2 \int_0^t \|S(t)\phi_{0,n} - S(t)\phi_0\| + \|S(t)\phi_0\|_{L^\infty(0,t;H_0^1)} \times \\
 & \quad \times \int_0^t \|S(t)\psi_{0,n} - S(t)\psi_0\| (\|S(t)\psi_{0,n}\|_{H_0^1} + \|S(t)\psi_0\|_{H_0^1}) \rightarrow 0. \tag{32}
 \end{aligned}$$

Following the same procedure for the proceeding integral implies

$$\int_0^t e^{-\delta(t-\tau)} \int S(t)\theta_{0,n} |S(t)\psi_{0,n}|^2 \rightarrow \int_0^t e^{-\delta(t-\tau)} \int S(t)\theta_0 |S(t)\psi_0|^2.$$

Furthermore,

$$\begin{aligned} & \left| \int_0^t e^{-\delta(t-\tau)} \int S(t)\theta_{0,n}S(\tau)\psi_{0x,n} - \int_0^t e^{-\delta(t-\tau)} \int S(t)\theta_0S(\tau)\psi_{0x} \right| \\ & \leq \|S(t)\psi_{0x,n}\|_{L^\infty(0,t;L^2)} \int_0^t \|S(t)\theta_{0,n} - S(t)\theta_0\| \\ & \quad + \|S(t)\theta_0\|_{L^\infty(0,t;L^2)} \int_0^t \|S(t)\psi_{0x} - S(t)\psi_{0x,n}\| \rightarrow 0. \end{aligned} \quad (33)$$

Therefore by relations (25) and (28)-(33) we obtain

$$\limsup_{n \rightarrow \infty} F_1(S(t)(\psi_{0,n}, \phi_{0,n}, \theta_{0,n})) \leq F_1(S(t)(\psi_0, \phi_0, \theta_0)). \quad (34)$$

But by relation (24) and the compact embedding $H^1 \hookrightarrow L^2$ we find that the following is true $S(t)(\psi_{0,n}, \phi_{0,n}) \rightarrow S(t)(\psi_0, \phi_0)$, strongly in L^2 ; therefore due to the above relation we have

$$\int \phi_{0,n}|\psi_{0,n}|^2 \rightarrow \int \phi_0|\psi_0|^2, \text{ and } \int f\overline{S(t)\psi_{0,n}} \rightarrow \int f\overline{S(t)\psi_0}.$$

Hence from the definition of F_1

$$\begin{aligned} & \limsup_{n \rightarrow \infty} (\kappa \|S(t)\psi_{0,n}\|_{H_0^1} + \|S(t)\theta_{0,n}\|^2 + \|S(t)\phi_{0,n}\|_{H_0^1}^2 \\ & \quad + (1 - \delta(\lambda - \delta))\|S(t)\phi_{0,n}\|^2) \\ & \leq (\kappa \|S(t)\psi_0\|_{H_0^1} + \|S(t)\theta_0\|^2 + \|S(t)\phi_0\|_{H_0^1}^2 + (1 - \delta(\lambda - \delta))\|S(t)\phi_0\|^2). \end{aligned}$$

But we may consider the right hand side of the relation above as the norm of $H_0^1 \times H_0^1 \times L^2$ and therefore without loss of generality

$$\limsup_{n \rightarrow \infty} \|S(t)(\psi_{0,n}, \psi_{0,n}, \theta_{0,n})\|_{H_0^1 \times H_0^1 \times L^2} \leq \|S(t)(\psi_0, \psi_0, \theta_0)\|_{H_0^1 \times H_0^1 \times L^2}.$$

Finally due to the weak convergence, we have completed the proof. \square

Theorem 3. *Let $f, g \in H_0^1(\Omega)$. The solutions $(\psi, \phi, \theta) \in C(\mathbb{R}^+, (H_0^1 \cap H^2)^2 \times H_0^1)$ of the problem (5)-(9) depend continuously on initial data in $(H_0^1 \cap H^2)^2 \times H_0^1$.*

Proof. The proof is analogue to the proof of Theorem 3.3 in [8]. \square

4. Existence of a Global Attractor. The aim of this section is to prove the existence of a global attractor for the dynamical system $S(t)$ in the space $(H_0^1 \cap H^2)^2 \times H_0^1$. Some of the ideas found here were earlier developed in the work by Karachalios and Stavrakakis [7]. To apply Proposition 1 below, it is necessary to prove the asymptotic compactness of the solutions in $(H_0^1 \cap H^2)^2 \times H_0^1$.

Theorem 4. *Let $f, g \in L^2(\Omega)$. Then the dynamical system $S(t)$ is asymptotically compact in $H_0^1 \times H_0^1 \times L^2$, that is if $\{(\psi_n, \phi_n, \theta_n)\}$ is bounded in $H_0^1 \times H_0^1 \times L^2$ and $t_n \rightarrow \infty$, then $\{S(t)(\psi_n, \phi_n, \theta_n)\}$ is precompact.*

Proof. Ideas developed in [1] will be used. Since sequence $(\psi_n, \phi_n, \theta_n)$ is bounded, there exists R such that $\|(\psi_n, \phi_n, \theta_n)\|_{H_0^1 \times H_0^1 \times L^2} \leq R$. Lemma 2 implies the existence of a constant $T(R)$ that

$$S(t)(\psi_n, \phi_n, \theta_n) \in B_1, \text{ for all } t \geq T(R), \quad (35)$$

where B_1 is the absorbing set given by relation (15). Since $t_n \rightarrow \infty$, there exists $N_1(R)$ such that if $n \geq N_1$, then $t_n \geq T(R)$, and thereby

$$S(t_n)(\psi_n, \phi_n, \theta_n) \in B_1, \quad \text{for all } n \geq N_1. \quad (36)$$

Hence there exists $(\psi, \phi, \theta) \in B_1$ such that

$$S(t_n)(\psi_n, \phi_n, \theta_n) \rightharpoonup (\psi, \phi, \theta), \quad \text{weakly in } H_0^1 \times H_0^1 \times L^2. \quad (37)$$

Since $t_n \rightarrow \infty$, for every $T > 0$, there exists $N_2(R, T)$ such that when $n \geq N_2$ one has $t_n - T \geq T(R)$. Therefore by relation (35)

$$S(t_n - T)(\psi_n, \phi_n, \theta_n) \in B_1 \quad \text{for all } n \geq N_2, \quad (38)$$

$$S(t_n - T)(\psi_n, \phi_n, \theta_n) \rightharpoonup (\psi_T, \phi_T, \theta_T), \quad \text{weakly in } H_0^1 \times H_0^1 \times L^2, \quad (39)$$

where $(\psi_T, \phi_T, \theta_T) \in B_1$. By relation (17) it follows that

$$S(T)(S(t_n - T)(\psi_n, \phi_n, \theta_n)) \rightharpoonup S(T)(\psi_T, \phi_T, \theta_T), \quad \text{weakly in } H_0^1 \times H_0^1 \times L^2, \quad (40)$$

and from the uniqueness of the solution we get that

$$(\psi, \phi, \theta) = S(T)(\psi_T, \phi_T, \theta_T). \quad (41)$$

Now from relation (37)

$$\liminf_{n \rightarrow \infty} \|S(t_n)(\psi_n, \phi_n, \theta_n)\|_{H_0^1 \times H_0^1 \times L^2} \geq \|(\psi, \phi, \theta)\|_{H_0^1 \times H_0^1 \times L^2}. \quad (42)$$

Let $S(T)(S(t_n - T)(\psi_n, \phi_n, \theta_n)) \in H_0^1 \times H_0^1 \times L^2$ be a solution of the system (5)-(9). Every solution satisfies (12). Hence relations (37) and (40) will give

$$\begin{aligned} F_1(S(t_n)(\psi_n, \phi_n, \theta_n)) &= e^{-\delta T} F_1(S(t_n - T)(\psi_n, \phi_n, \theta_n)) \\ &\quad + \int_0^T e^{-\delta(T-\tau)} G_1(S(\tau)(S(t_n - T)(\psi_n, \phi_n, \theta_n))) d\tau. \end{aligned} \quad (43)$$

Now since relation (38) holds, $S(t_n - T)(\psi_n, \phi_n, \theta_n)$ is bounded and therefore $e^{-\delta t} F_1(S(t_n - T)(\psi_n, \phi_n, \theta_n)) \leq C e^{\delta T}$. Estimating the second term of (43) as in Theorem 2 implies that

$$\begin{aligned} \limsup_{n \rightarrow \infty} \int_0^T e^{-\delta(T-\tau)} G_1(S(\tau)(S(t_n - T)(\psi_n, \phi_n, \theta_n))) d\tau \\ \leq \int_0^T e^{-\delta(T-\tau)} G_1(S(\tau)(\psi_T, \phi_T, \theta_T)) d\tau. \end{aligned} \quad (44)$$

Therefore

$$\begin{aligned} \limsup_{n \rightarrow \infty} F_1(S(T)(S(t_n - T)(\psi_n, \phi_n, \theta_n))) \\ \leq C e^{\delta T} + \int_0^T e^{\delta(T-\tau)} G_1(S(T)(\psi_T, \phi_T, \theta_T)) d\tau. \end{aligned} \quad (45)$$

Furthermore, for the solution $(\psi, \phi, \theta) = S(T)(\psi_T, \phi_T, \theta_T)$ we have

$$F_1(\psi, \phi, \theta) = e^{-\delta T} F_1(\psi_T, \phi_T, \theta_T) + \int_0^T e^{-\delta(T-\tau)} G_1(S(\tau)(\psi_T, \phi_T, \theta_T)) d\tau. \quad (46)$$

Substituting relation (46) into (45) implies

$$\limsup_{n \rightarrow \infty} F_1(S(t_n)(\psi_n, \phi_n, \theta_n)) \leq C_1 e^{\delta T} + F_1(\psi, \phi, \theta), \quad (47)$$

where $e^{\delta T} F_1(\psi_T, \phi_T, \theta_T) \leq C_1 e^{\delta T}$. Let $T \rightarrow +\infty$, then

$$\limsup_{n \rightarrow \infty} F_1(S(t_n)(\psi_n, \phi_n, \theta_n)) \leq F_1(\psi, \phi, \theta).$$

The rest of the proof follows the same steps as in Theorem 2. \square

Theorem 5. *Assume that $f, g \in H_0^1(\Omega)$. Then the dynamical system $S(t)$ is asymptotically compact in $(H_0^1 \cap H^2)^2 \times H_0^1$.*

Proof. The proof is omitted as it follows similar steps to Theorem 4. \square

Proposition 1. *Assume that X is a metric space and $\{S(t)\}_{t \geq 0}$ is a semigroup of continuous operators in X . If $\{S(t)\}_{t \geq 0}$ has a bounded absorbing set and is asymptotically compact, then $\{S(t)\}_{t \geq 0}$ possesses a global attractor which is a compact invariant set and attracts every bounded set in X .*

Theorem 6. *Assume that $f, g \in H_0^1(\Omega)$. Then the problem (5)-(9) possesses a strong compact global attractor in $(H_0^1 \cap H^2)^2 \times H_0^1$, which is a compact invariant subset and attracts every bounded set in the norm topology of $(H_0^1 \cap H^2)^2 \times H_0^1$.*

Proof. Taking into consideration the asymptotic compactness of $S(t)$ in $H_0^1 \times H_0^1 \times L^2$ (Theorem 4), the asymptotic compactness of $S(t)$ in $(H_0^1 \cap H^2)^2 \times H_0^1$ (Theorem 5) and Proposition 1 the proof is straight forward. \square

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