

# Sub and Supersolutions for Semilinear Elliptic Equations on all of $R^n$

K. J. BROWN and N. STAVRAKAKIS\*

Department of Mathematics, Heriot-Watt University

Riccarton, Edinburgh EH14 4AS, UK

{ Differential Integral Equations, Vol 7 (1994), no. 5-6, 12151225 }

*This paper is dedicated to the memory of Peter Hess.*

## Abstract

Sub and supersolutions are constructed for the semilinear elliptic equation  $-\Delta u = \lambda g(x)f(u)$  on all of  $\mathcal{R}^n$  which arises in population genetics. It is shown that the theory of existence of solutions is very different in the case  $n = 1$  or  $2$  and in the case  $n \geq 3$ .

## 1 Introduction

In this paper we shall discuss the construction of sub- and supersolutions as well as the existence and nonexistence of solutions of the equation

$$-\Delta u = \lambda g(x)f(u), \quad 0 < u < 1, \quad x \in \mathcal{R}^n, \quad (1.1)_\lambda$$

which arises in population genetics (see [1, 3]). The unknown function  $u$  corresponds to the relative frequency of an allele and is hence constrained to have values between 0 and 1. The real parameter  $\lambda > 0$  corresponds to the reciprocal of a diffusion coefficient so that the case of small  $\lambda$  considered in

---

\*on leave during 1993 from the Department of Mathematics, National Technical University, Zografou Campus, 157 80 Athens, GREECE.

AMS Subject Classification : 35J60.

this paper corresponds to diffusion being large. We assume throughout that  $g$  satisfies

- (G)  $g : \mathcal{R}^n \rightarrow \mathcal{R}$  is smooth such that  $g(x_0) > 0$  for some  $x_0 \in \mathcal{R}^n$  and there exists  $R_0 > 0$  such that  $g(x) < 0$  whenever  $|x| > R_0$ .

This assumption corresponds to the fact that an allele has an advantage at some points  $x$  in  $\mathcal{R}^n$  (where  $g(x) > 0$ ), but is disadvantaged for  $|x| > R_0$ . In the population genetics model  $f$  is considered to be the cubic function  $f(u) = u(1-u)[h(1-u) + (1-h)u]$ , for some constant  $h$ ,  $0 < h < 1$ . We shall assume throughout that  $f$  satisfies the condition

- (F)  $f : [0, 1] \rightarrow \mathcal{R}$  is a smooth function such that  $f(0) = f(1) = 0$ ,  $f'(0) > 0$ ,  $f'(1) < 0$ , and  $f(u) > 0$  for all  $0 < u < 1$ .

We shall extend and unify existing results on solutions of  $(1.1)_\lambda$  (see [1, 2, 3, 6, 7]) by constructing some new sub- and supersolutions for the problem. The results obtained show that the existence theory for solutions of  $(1.1)_\lambda$  is very different in the case  $n = 1, 2$  and the case  $n \geq 3$ . It is easy to show (see [1]) that sub- and supersolutions always exist for  $(1.1)_\lambda$  when  $\lambda$  is sufficiently large. We shall be interested in constructing such solutions when  $\lambda$  is small and as a means of doing so we first construct numbers  $\lambda^*$ ,  $\lambda_* \geq 0$  such that a supersolution (respectively subsolution) of  $(1.1)_\lambda$  exists provided that  $\lambda > \lambda^*$  (respectively  $\lambda > \lambda_*$ ). First we recall how a class of subsolutions is constructed in [1]. Let  $R > 0$  and let  $\underline{u}$  be defined by

$$\underline{u}(x) = \begin{cases} \varphi(x), & \text{if } |x| \leq R \\ 0, & \text{if } |x| > R \end{cases},$$

where  $\varphi$  is a positive solution of

$$\begin{aligned} -\Delta\varphi(x) &= \lambda g(x)f(\varphi(x)), & \text{if } |x| < R \\ \varphi(x) &= 0, & \text{if } |x| = R. \end{aligned}$$

Such a solution  $\varphi$  exists provided  $\lambda > \lambda_1(R)$  where  $\lambda_1(R)$  is the principal eigenvalue of the problem

$$\begin{aligned} -\Delta\psi(x) &= \lambda g(x)f'(0)\psi(x), & \text{if } |x| < R \\ \psi(x) &= 0, & \text{if } |x| = R. \end{aligned}$$

Since

$$\lambda_1(R) = \inf \left\{ \frac{\int_{B_R} |\nabla u(x)|^2 dx}{\int_{B_R} g(x) f'(0) u^2(x) dx} : u \in H_0^1(B_R), \int_{B_R} g(x) u^2(x) dx > 0 \right\}$$

where  $B_R = \{x \in \mathcal{R}^n : |x| \leq R\}$ ,  $\lambda_1(R)$  is a decreasing function of  $R$  and we define  $\lambda_* = \lim_{R \rightarrow \infty} \lambda_1(R)$ . Thus if  $\lambda > \lambda_*$  we can choose  $R$  such that  $\lambda > \lambda_1(R)$ , and then construct a subsolution  $\underline{u}(x)$  as described above. In particular when  $\lambda_* = 0$  we can construct such a subsolution for any  $\lambda > 0$ .

We now construct supersolutions which are identically equal to 1 on an exterior domain in a similar way. If we define

$$\bar{u}(x) = \begin{cases} 1 - \varphi(x) & \text{if } |x| \leq R \\ 1 & \text{if } |x| > R \end{cases},$$

then  $\bar{u}(x)$  is a supersolution of (1.1) $_\lambda$  if  $\varphi$  is a positive solution of

$$\begin{aligned} -\Delta \varphi(x) &= \lambda h(x) \hat{f}(\varphi(x)), & \text{if } |x| < R \\ \varphi(x) &= 0, & \text{if } |x| = R, \end{aligned}$$

where  $h(x) = -g(x)$  and  $\hat{f}(u) = f(1 - u)$ . Note that  $\hat{f}'(0) = -f'(1) > 0$ . Using an argument very similar to that used above, it can be shown that such a supersolution can be constructed provided that  $\lambda > \lambda^*$  where  $\lambda^* = \lim_{R \rightarrow \infty} \hat{\lambda}_1(R)$ , and  $\hat{\lambda}_1(R)$  is the principal eigenvalue of the problem

$$\begin{aligned} -\Delta \psi(x) &= \lambda h(x) \hat{f}'(0) \psi(x), & \text{if } |x| < R \\ \psi(x) &= 0, & \text{if } |x| = R, \end{aligned}$$

and so

$$\hat{\lambda}_1(R) = \inf \left\{ \frac{\int_{B_R} |\nabla u(x)|^2 dx}{\int_{B_R} h(x) \hat{f}'(0) u^2(x) dx} : u \in H_0^1(B_R), \int_{B_R} h(x) u^2(x) dx > 0 \right\}.$$

If  $\lambda > \lambda_*$ , it is easy to see that by an appropriate choice of  $R$  we can construct an arbitrarily small subsolution, and if  $\lambda > \lambda^*$  that we can construct a supersolution, which is arbitrarily close to 1. Thus we have

**Theorem 1.1** *If  $\lambda > \max\{\lambda^*, \lambda_*\}$ , then there exists a solution of (1.1) $_\lambda$ . In particular, if  $\lambda^* = \lambda_* = 0$ , then (1.1) $_\lambda$  has a solution for all  $\lambda > 0$ .*

Thus it is of interest to find conditions under which  $\lambda_* = 0$  or  $\lambda^* = 0$ . We investigate this problem in Section 2 and the results we obtain depend heavily on whether  $n = 1, 2$  or  $n \geq 3$ , as well as on the sign of  $\int_{\mathcal{R}^n} g(x) dx$ .

In Section 3 we prove some existence and nonexistence results which are suggested by the results of Section 2. In particular we show that when  $n = 1, 2$ , then  $(1.1)_\lambda$  has a solution for all  $\lambda > 0$  when  $\int_{\mathcal{R}^n} g(x) dx \geq 0$ , but has no solution for sufficiently small  $\lambda$  when  $\int_{\mathcal{R}^n} g(x) dx < 0$ . In contrast when  $n \geq 3$ ,  $g$  is small at infinity (viz.  $|g(x)| \leq k(1 + |x|^2)^{-\alpha}$ , for some  $\alpha > 1$  and  $k > 0$ ) and  $\lambda$  sufficiently small, then  $(1.1)_\lambda$  has no solution  $u$  such that  $\lim_{|x| \rightarrow \infty} u(x) = 0$ , but has a solution  $u$  such that  $\lim_{|x| \rightarrow \infty} u(x) = c$  for any constant  $c$ ,  $0 < c < 1$ .

## 2 Sub and supersolutions for small $\lambda$ .

First we consider the case where  $\int_{\mathcal{R}^n} g(x) dx < 0$ .

**Theorem 2.1** *Suppose that  $\int_{\mathcal{R}^n} g(x) dx < 0$ . Then*

- (i)  $\lambda_* > 0$ , and
- (ii)  $\lambda^* = 0$ , when  $n = 1, 2$ .

*Proof* (i) Choose  $R_1 > R_0$  such that  $\int_{B_{R_1}} g(x) dx < 0$ . By [1] (Lemma 2.7) there exists a constant  $K > 0$  such that

$$\int_{B_{R_1}} |\nabla u(x)|^2 dx \geq K \int_{B_{R_1}} u^2(x) dx$$

for all  $u \in H^1(B_{R_1})$  which satisfy  $\int_{B_{R_1}} g(x) u^2(x) dx > 0$ . Suppose that  $R > R_1$  and  $u \in H_0^1(B_R)$  such that  $\int_{B_R} g(x) u^2(x) dx > 0$ . Then  $u \in H^1(B_{R_1})$ , and since  $g(x) < 0$  for  $R_1 \leq |x| \leq R$ ,  $\int_{B_{R_1}} g(x) u^2(x) dx > 0$ . Hence

$$\begin{aligned} \int_{B_R} |\nabla u(x)|^2 dx &\geq \int_{B_{R_1}} |\nabla u(x)|^2 dx \\ &\geq K \int_{B_{R_1}} u^2(x) dx \geq KK_1 \int_{B_{R_1}} g(x) u^2(x) dx, \\ &\geq KK_1 \int_{B_R} g(x) u^2(x) dx \end{aligned}$$

for a suitable constant  $K_1$ . Thus

$$\frac{\int_{B_R} |\nabla u(x)|^2 dx}{\int_{B_R} g(x) u^2(x) dx} \geq KK_1 \text{ for all } u \in H_0^1(B_R) \text{ such that } \int_{B_R} g(x) u^2(x) dx > 0,$$

and so  $\lambda_1(R) \geq KK_1$ . Since this holds for all  $R > R_1$ , we conclude that  $\lambda_* \geq KK_1 > 0$ .

(ii) We consider the case  $n = 2$ . Suppose that  $\varepsilon > 0$  is arbitrary. Since  $\int_{\mathcal{R}^n} g(x)dx < 0$ , there exists  $R > R_0$  and a constant  $a > 0$ , such that  $\int_{B_R} h(x)dx > a$ .

We define a radially symmetric function  $u$  as follows

$$\begin{aligned} u(r) &= 1, & \text{if } r \leq R \\ u'(r) &= -(\varepsilon/r), & \text{if } R \leq r \leq Z \\ u(r) &= 0, & \text{if } r \geq Z, \end{aligned}$$

where  $Z$  is chosen so that  $u$  is continuous. Then  $u$  is a decreasing function for  $R \leq r \leq Z$ . Since  $u(r) = -\varepsilon \ln r + \beta$ , for some positive constant  $\beta$ , we must have that

$$1 = -\varepsilon \ln R + \beta, \quad 0 = -\varepsilon \ln Z + \beta,$$

and so

$$\varepsilon (\ln Z - \ln R) = 1.$$

Then, if  $r > Z$ ,

$$\begin{aligned} \int_{B_r} |\nabla u(x)|^2 dx &= \int_0^r r u_r^2(r) dr = \int_R^Z (\varepsilon^2/r) dr \\ &= \varepsilon^2 (\ln Z - \ln R) = \varepsilon, \end{aligned}$$

and

$$\begin{aligned} \int_{B_r} h(x) \hat{f}'(0) u^2(x) dx &\geq \hat{f}'(0) \int_{B_R} h(x) u^2(x) dx \\ &= \hat{f}'(0) \int_{B_R} h(x) dx \geq \hat{f}'(0) a. \end{aligned}$$

Hence, if  $r > Z$ , then  $\lambda_1(r) \leq \varepsilon/\hat{f}'(0)a$ . Since  $\varepsilon > 0$  is arbitrary, it follows that  $\lambda^* = 0$ .

When  $n = 1$  a similar but simpler argument, in which  $u(r) = -\varepsilon r + \beta$  on its nonconstant part, can be used.  $\diamond$

It does not seem possible to show, by using an argument similar to that above, that  $\lambda^* = 0$  when  $n \geq 3$ ; it is however easy to obtain supersolutions

for all  $\lambda > 0$  when  $n \geq 3$  as for this case, since  $u(x) = 1/|x|^{n-2}$  satisfies  $\Delta u(x) = 0$ , then

$$\underline{u}(x) = \begin{cases} 1, & \text{if } |x| \leq R_0 \\ (R_0/|x|)^{n-2}, & \text{if } |x| > R_0 \end{cases},$$

is always a supersolution.

As the following theorem shows, it is also possible to have  $\lambda^* = 0$  for  $n = 1, 2$  and so obtain supersolutions for arbitrarily small  $\lambda$ , without assuming that  $\int_{\mathcal{R}^n} g(x) dx < 0$ .

**Theorem 2.2** (i) If  $n = 1$  and  $\lim_{|x| \rightarrow \infty} |x|^2 g(x) = -\infty$ , then  $\lambda^* = 0$ .  
(ii) If  $n = 2$  and  $\lim_{|x| \rightarrow \infty} |x|^2 [\ln(|x|)]^2 g(x) = -\infty$ , then  $\lambda^* = 0$ .

*Proof* (i) First we consider the case  $n = 1$ . Let  $\varepsilon > 0$  be arbitrary. Then there exists  $R > R_0$  such that  $h(x) > 1/\varepsilon x^2$  if  $|x| \geq R$ . We define a test function as follows

$$\phi(x) = \begin{cases} 0, & \text{if } -\infty \leq x \leq R_0 \\ \frac{x-R_0}{R-R_0}, & \text{if } R_0 \leq x \leq R \\ 1, & \text{if } R \leq x \leq 2R \\ \frac{3R-R_0-x}{R-R_0}, & \text{if } 2R \leq x \leq 3R-R_0 \\ 0, & \text{if } x \geq 3R-R_0 \end{cases},$$

Then

$$\int_{\mathcal{R}} [\phi_x(x)]^2 dx = \frac{2}{R-R_0}$$

and

$$\int_{\mathcal{R}} h(x) [\phi(x)]^2 dx \geq \int_R^{2R} h(x) dx \geq \frac{1}{\varepsilon} \int_R^{2R} \frac{1}{x^2} dx = \frac{1}{2\varepsilon R}$$

Hence

$$\frac{\int_{\mathcal{R}} [\phi_x(x)]^2 dx}{\int_{\mathcal{R}} h(x) \hat{f}'(0) \phi^2(x) dx} \leq \frac{4\varepsilon R}{\hat{f}'(0)(R-R_0)} \leq \frac{4\varepsilon}{\hat{f}'(0)},$$

and so  $\lambda^* \leq 4\varepsilon/\hat{f}'(0)$ . Since  $\varepsilon > 0$  is arbitrary, we obtain  $\lambda^* = 0$ .

(ii) A similar argument shows that  $\lambda^* = 0$  when  $n = 2$  by replacing the functions

$$\frac{x-R_0}{R-R_0} \quad \text{and} \quad \frac{3R-R_0-x}{R-R_0},$$

by the functions

$$\frac{\ln |x| - \ln R_0}{\ln R - \ln R_0} \quad \text{and} \quad \frac{3 \ln R - \ln R_0 - \ln |x|}{\ln R - \ln R_0},$$

respectively, and using the ranges  $R_0 \leq |x| \leq R$ ,  $R \leq |x| \leq R^2$ , and  $R^2 \leq |x| \leq R^3/R_0$ .  $\diamond$

Suppose now that  $\int_{\mathcal{R}^n} g(x)dx \geq 0$ . It is proved in [1] (Lemma 4.4) that when  $n = 1, 2$  and  $\int_{\mathcal{R}^n} g(x)dx > 0$ , then  $\lambda_* = 0$ . We now discuss the more delicate case where  $\int_{\mathcal{R}^n} g(x)dx = 0$ .

**Theorem 2.3** *Suppose that  $\int_{\mathcal{R}^n} g(x)dx = 0$ . Then  $\lambda_* = 0$ , if*

- (i)  $n = 1$  and  $\int_{\mathcal{R}} (\ln |x|)^2 g(x)dx$  converges, or  
(ii)  $n = 2$  and  $\int_{\mathcal{R}^2} [\ln(|\ln |x||)]^2 g(x)dx$  converges.

*Proof* (i) We consider a test function of the form

$$u(x) = \begin{cases} 1, & \text{for } |x| \leq R_0 \\ \zeta - \delta \ln |x|, & \text{for } R_0 \leq |x| \leq R \\ 0, & \text{for } |x| \geq R \end{cases},$$

where  $\delta, \zeta$  are constants chosen so that  $u$  is a continuous function, i.e.,  $\delta = 1/(\ln R - \ln R_0)$  and  $\zeta = \ln R/(\ln R - \ln R_0)$  and show that

$$\lim_{R \rightarrow \infty} \frac{\int_{\mathcal{R}} [u_x(x)]^2 dx}{\int_{\mathcal{R}} g(x) f'(0) u^2(x) dx} = 0.$$

Now

$$\int_{\mathcal{R}} [u_x(x)]^2 dx = 2 \int_{R_0}^R \left(\frac{\delta}{x}\right)^2 dx = 2\delta^2 \left[\frac{1}{R_0} - \frac{1}{R}\right] = \frac{2\delta^2(R - R_0)}{RR_0},$$

and

$$\begin{aligned} & \int_{\mathcal{R}} g(x) f'(0) u^2(x) dx \\ &= f'(0) \left\{ \int_{|x| \leq R_0} g(x) dx + \int_{R_0 \leq |x| \leq R} g(x) (\zeta - \delta \ln |x|)^2 dx \right\} \\ &= f'(0) \left\{ \int_{|x| \leq R_0} g(x) dx + \int_{R_0 \leq |x| \leq R} g(x) [\zeta^2 - 2\delta\zeta \ln |x| + \delta^2 (\ln |x|)^2] dx \right\}. \end{aligned}$$

Hence

$$\begin{aligned}
\frac{\int_{\mathcal{R}} g(x) f'(0) u^2(x) dx}{\int_{\mathcal{R}} [u_x(x)]^2 dx} &= \frac{f'(0) R R_0}{2(R-R_0)} \left\{ (\ln R - \ln R_0)^2 \int_{|x| \leq R_0} g(x) dx \right. \\
&\quad \left. + \int_{R_0 \leq |x| \leq R} g(x) [(\ln R)^2 - 2 \ln R \ln |x| + (\ln |x|)^2] dx \right\} \\
&= \frac{f'(0) R R_0}{2(R-R_0)} \left\{ (\ln R)^2 \int_{|x| \leq R} g(x) dx + (\ln R_0)^2 \int_{|x| \leq R_0} g(x) dx \right. \\
&\quad \left. + \int_{R_0 \leq |x| \leq R} (\ln |x|)^2 g(x) dx - 2 \ln R_0 \ln R \int_{|x| \leq R_0} g(x) dx \right. \\
&\quad \left. - 2 \ln R \int_{R_0 \leq |x| \leq R} \ln |x| g(x) dx \right\} \\
&\equiv \frac{f'(0) R R_0}{2(R-R_0)} \{A_1(R) + A_2 + A_3(R) + A_4(R) + A_5(R)\}.
\end{aligned}$$

Since  $\int_{\mathcal{R}} g(x) dx = 0$ ,  $A_1(R) > 0$ , for all  $R > R_0$ . Since we are assuming that  $\int_{\mathcal{R}} (\ln |x|)^2 g(x) dx$  converges,  $A_3(R)$  is uniformly bounded. Finally

$$A_4(R) + A_5(R) = -2 \ln R_0 \ln R \int_{|x| \leq R} \psi(x) g(x) dx,$$

where

$$\psi(x) = \begin{cases} 1, & \text{for } 0 \leq |x| \leq R_0 \\ \ln |x| / \ln R_0, & \text{for } R_0 \leq |x| \leq R \end{cases},$$

Since  $\int_{\mathcal{R}} g(x) dx = 0$ , it is clear that  $\int_{\mathcal{R}} \psi(x) g(x) dx < 0$  and so  $\int_{|x| \leq R} \psi(x) g(x) dx$  is negative and uniformly bounded away from zero when  $R$  is sufficiently large. Hence  $\lim_{R \rightarrow \infty} (A_4(R) + A_5(R)) = \infty$ , and so

$$\lim_{R \rightarrow \infty} \frac{\int_{\mathcal{R}} [u_x(x)]^2 dx}{\int_{\mathcal{R}} g(x) f'(0) u^2(x) dx} = 0.$$

Thus  $\lambda_* = 0$ .

(ii) When  $n = 2$ , a similar argument shows that  $\lambda_* = 0$  by replacing the test function  $\zeta - \delta \ln |x|$  by  $\zeta - \delta \ln(| \ln |x| |)$ .  $\diamond$

These results, that  $\lambda_* = 0$  when  $\int_{\mathcal{R}^n} g(x) dx \geq 0$ , cannot be extended to the case where  $n \geq 3$  because the nonexistence results in the next section imply that when  $n \geq 3$  and  $g$  is sufficiently small at infinity then  $\lambda_* > 0$ , no matter what the sign of  $\int_{\mathcal{R}^n} g(x) dx$ .

### 3 Existence and nonexistence of solutions.

We shall first consider the case of  $n = 1, 2$  and show how the existence theory for  $(1.1)_\lambda$  is heavily dependent on the sign of  $\int_{\mathcal{R}^n} g(x)dx$ . The following results are simple consequences of the sufficient conditions for  $\lambda_\star = 0, \lambda^\star = 0$  obtained in Section 2.

**Theorem 3.1** *Suppose that  $n = 1$ . Then  $(1.1)_\lambda$  has a solution for all  $\lambda > 0$ , provided that*

(i)  $\int_{\mathcal{R}} g(x)dx > 0$

or

$\int_{\mathcal{R}} g(x)dx = 0$  and  $\int_{\mathcal{R}} (\ln |x|)^2 g(x)dx$  converges,

and

(ii)  $\lim_{|x| \rightarrow \infty} |x|^2 g(x) = -\infty$ .

A similar result holds when  $n = 2$  and the hypotheses that  $\int_{\mathcal{R}} (\ln |x|)^2 g(x)dx$  converges and  $\lim_{|x| \rightarrow \infty} |x|^2 g(x) = -\infty$  are replaced by  $\int_{\mathcal{R}^2} [\ln(|\ln |x||)]^2 g(x)dx$  converges and  $\lim_{|x| \rightarrow \infty} |x|^2 [\ln(|x|)]^2 g(x) = -\infty$ .

The  $\int_{\mathcal{R}} g(x)dx > 0$  case of Theorem 3.1 was proved in [1] by constructing a supersolution, using phase plane analysis.

The hypotheses of Theorem 3.1 can be satisfied provided  $g$  is small, but not too small at infinity, e.g.  $g(x) \sim 1/x^\alpha$ , when  $n = 1$ , and  $g(x) \sim 1/x^2 (\ln x)^\alpha$ , when  $n = 2$ , where  $1 < \alpha < 2$ .

It was shown in Section 2 that, when  $\int_{\mathcal{R}^n} g(x)dx < 0$ , then  $\lambda^\star = 0$  but  $\lambda_\star > 0$ . It is still possible a priori that some other form of subsolution can be constructed or that solutions of  $(1.1)_\lambda$  exist for  $\lambda < \lambda_\star$ . The following result shows, however, that solutions cannot exist for arbitrarily small  $\lambda > 0$ .

**Theorem 3.2** *Suppose that  $n = 1, 2$ ,  $\int_{\mathcal{R}^n} g(x)dx < 0$  and  $f$  satisfies  $2f(u) - uf'(u) > 0$  for  $0 < u < 1$ . Then there exists  $\lambda_0 > 0$  such that  $(1.1)_\lambda$  has no solution  $u$  whenever  $0 < \lambda < \lambda_0$ .*

*Proof* We shall prove the result for the case  $n = 2$ ; a similar but simpler proof holds when  $n = 1$ . Suppose that  $u$  is a solution of  $(1.1)_\lambda$ . It is shown in [7] (Lemma 3.2, Lemma 3.3) that  $\nabla u \in L^2(\mathcal{R}^2)$ ,  $gf(u) \in L^1(\mathcal{R}^2)$  and  $\lim_{R \rightarrow \infty} \int_{\partial B_R} u(x) |\nabla u(x)| dS = 0$ . Firstly we shall show that  $\int_{\mathcal{R}^2} g(x)u^2(x)dx > 0$ . Let  $w = (u^2/f(u))$ . Since  $u$  is subharmonic whenever  $|x| > R_0$ , it follows from the Hadamard Three Circles Theorem ([5], p.130)

that  $\sup_{|x|=R} u(x)$  is a decreasing function of  $R$  and so there exists a constant  $k^*$  such that  $u(x) \leq k^* < 1$  for all  $x \in \mathcal{R}^2$ . Hence  $w$  is a smooth bounded function on  $\mathcal{R}^2$ . Thus

$$\begin{aligned}
& \lim_{R \rightarrow \infty} \lambda \int_{B_R} g(x) u^2(x) dx \\
&= \lim_{R \rightarrow \infty} \lambda \int_{B_R} g(x) f(u) w dx = \lim_{R \rightarrow \infty} \int_{B_R} (-\Delta u) w dx \\
&= \lim_{R \rightarrow \infty} \left\{ - \int_{\partial B_R} (\partial u / \partial n) w dS + \int_{B_R} \nabla u \cdot \nabla w dx \right\} \\
&= \lim_{R \rightarrow \infty} \left\{ - \int_{\partial B_R} (\partial u / \partial n) u (f(u) / u) dS \right. \\
&\quad \left. + \int_{B_R} |\nabla u|^2 u [2f(u) - u f'(u)] [f^{-2}(u)] dx \right\}.
\end{aligned}$$

Since

$$\left| \int_{\partial B_R} \frac{\partial u}{\partial n} u \frac{f(u)}{u} dS \right| \leq \left| \int_{\partial B_R} |\nabla u| u \frac{f(u)}{u} dS \right| \rightarrow 0 \text{ as } R \rightarrow \infty,$$

and  $2f(u) - u f'(u) > 0$  for  $0 < u < 1$ , it follows that  $\int_{\mathcal{R}^2} g(x) u^2(x) dx > 0$ .

Now choose a ball  $B$  such that  $\int_B g(x) dx < 0$  and  $g(x) < 0$  whenever  $x \notin B$ . By [1] (Lemma 2.7) there exists  $K > 0$  such that  $\int_B g(x) v^2(x) dx > K \int_B v^2(x) dx$  for all  $v \in H^1(B)$  such that  $\int_B g(x) v^2(x) dx > 0$ . Clearly we have  $\int_B g(x) u^2(x) dx > 0$  and so

$$\begin{aligned}
\int_{\mathcal{R}^2} |\nabla u(x)|^2 dx &\geq \int_B |\nabla u(x)|^2 dx \geq K \int_B u^2(x) dx \\
&\geq K K^* \int_B g(x) f(u) u(x) dx \geq \gamma \int_{\mathcal{R}^2} g(x) f(u) u(x) dx,
\end{aligned}$$

where  $K^*$  is chosen so that  $g(x) f(u) \leq u / K^*$  for all  $x \in B$  and  $0 < u < 1$  and  $\gamma = K K^*$  depends only on  $f$  and  $g$ , but is independent of  $u$ . On the other hand multiplying (1.1) $_\lambda$  by  $u$  and integrating gives that

$$\int_{\mathcal{R}^2} |\nabla u(x)|^2 dx - \lim_{R \rightarrow \infty} \int_{\partial B_R} \frac{\partial u}{\partial n} u dS = \lambda \int_{\mathcal{R}^2} g(x) f(u) u(x) dx.$$

Thus we must have  $\lambda \geq \gamma$  and so the proof is complete.  $\diamond$

The hypothesis  $2f(u) - uf'(u) > 0$  is a weak concavity condition and is satisfied by the cubic function  $f$  arising in the population genetics model, viz.,  $f(u) = u(1-u)[h(1-u) + (1-h)u]$ . A more precise nonexistence result is obtained in [7] (Theorem 4.3), but under more restrictive assumptions on  $f$  than those used here.

The above theorem implies that, when  $n = 1, 2$ , there exist examples of functions  $g$  decaying arbitrarily fast at infinity such that no solution of  $(1.1)_\lambda$  exists if  $\lambda$  is sufficiently small. Moreover, at least in the radial case, the solutions obtained under the hypotheses of Theorem 3.1 will approach 0 as  $|x|$  tends to infinity (see [2]). We now consider the case where  $n \geq 3$  and  $g$  is small at infinity and show that completely different results hold.

We shall assume that the function  $g$  is small in the following sense

$$(G_1) \quad |g(x)| \leq k(1 + |x|^2)^{-\alpha} \quad \text{for some constants } k > 0, \text{ and } \alpha > 1.$$

Our proofs shall make use of various properties of Newtonian potentials, which are proved in [4].

**Theorem 3.3** *Suppose that  $n \geq 3$  and  $g$  satisfies  $(G_1)$ . Then there exists  $\lambda_0 > 0$  such that, whenever  $0 < \lambda < \lambda_0$ , there does not exist a solution  $u$  of  $(1.1)_\lambda$  with  $\lim_{|x| \rightarrow \infty} u(x) = 0$ .*

*Proof* Suppose that  $u$  is a solution of  $(1.1)_\lambda$  such that  $\lim_{|x| \rightarrow \infty} u(x) = 0$ . It follows from [4] (Lemma 2.3) that  $u$  satisfies

$$u(x) = c_n \int_{\mathcal{R}^n} \frac{g(y)f(u(y))}{|x-y|^{n-2}} dy, \quad (3.1)$$

where  $c_n = [n(n-2)\omega_n]^{-1}$  and  $\omega_n$  is the volume of the unit ball in  $\mathcal{R}^n$ . Since  $|g(y)f(u(y))| \leq k_1|y|^{-2\alpha}$  at  $\infty$ , we have  $|u(x)| \leq k_1|x|^{-\beta}$ , where  $\beta = n-2$  if  $2\alpha > n$  and  $\beta = 2-2\alpha$  if  $2\alpha < n$ . Since  $f(u(y)) \leq c^*u(y)$ , for some constant  $c^*$ , it can be proved by using a bootstrapping argument that  $u(x) \leq k_2|x|^{2-n}$ , for some constant  $k_2$ . Moreover it can be shown, by differentiating (3.1) and using arguments similar to those used above, that  $|\nabla u(x)| \leq k_3|x|^{1-n}$ .

Since  $g$  satisfies  $(G_1)$ ,  $g$  lies  $L^{n/2}(\mathcal{R}^n)$ . By the estimates on  $u$  obtained above we have  $\nabla u \in L^2(\mathcal{R}^n)$ ,  $u \in L^q(\mathcal{R}^n)$ , where  $q = 2n/(n-2)$ . Hence there exists a sequence  $\{u_k\} \subset C_0^\infty(\mathcal{R}^n)$ , such that  $\nabla u_k \rightarrow \nabla u$

in  $L^2(\mathcal{R}^n)$  and  $u_k \rightarrow u$  in  $L^q(\mathcal{R}^n)$ . Thus  $u_k^2 \rightarrow u^2$  in  $L^{n/(n-2)}(\mathcal{R}^n)$  and so  $\lim_{k \rightarrow \infty} \int_{\mathcal{R}^n} |g|u_k^2 dx = \int_{\mathcal{R}^n} |g|u^2 dx$ . By Hardy's inequality there exists  $d > 0$  such that

$$\int_{\mathcal{R}^n} |\nabla v(x)|^2 dx \geq d \int_{\mathcal{R}^n} \frac{v^2(x)}{1+|x|^2} dx$$

for all  $v \in C_0^\infty(\mathcal{R}^n)$ . Hence

$$\begin{aligned} \int_{\mathcal{R}^n} |\nabla u(x)|^2 dx &= \lim_{k \rightarrow \infty} \int_{\mathcal{R}^n} |\nabla u_k(x)|^2 dx \geq d \int_{\mathcal{R}^n} u_k^2(x)/(1+|x|^2) dx \\ &\geq (d/k) \lim_{k \rightarrow \infty} \int_{\mathcal{R}^n} |g(x)|u_k^2(x) dx = (d/k) \int_{\mathcal{R}^n} |g(x)|u^2(x) dx. \end{aligned}$$

But multiplying (1.1) $_\lambda$  by  $u$  and integrating gives

$$\int_{\mathcal{R}^n} |\nabla u(x)|^2 dx - \lim_{R \rightarrow \infty} \int_{\partial B_R} \frac{\partial u}{\partial n} u dS = \lambda \int_{\mathcal{R}^n} g(x) f(u) u(x) dx.$$

Since the integral over the boundary tends to 0, it follows that

$\int_{\mathcal{R}^n} |\nabla u(x)|^2 dx \leq \lambda c^* \int_{\mathcal{R}^n} |g(x)|u^2(x) dx$ ,  
for all  $0 < u < 1$ . This is impossible if  $\lambda c^* < d/k$ , i.e., if  $\lambda < h(d/c^*k)$   
and so the proof is complete.  $\diamond$

Finally we prove, for arbitrarily small  $\lambda$ , the existence of solutions of (1.1) $_\lambda$  which approach nonzero constants as  $|x| \rightarrow \infty$ .

**Theorem 3.4** *Suppose that  $n \geq 3$  and  $g$  satisfies  $(G_1)$ . Let  $c$  be given constant such that  $0 < c < 1$ . If  $\lambda$  is sufficiently small, there exists a solution  $u$  of (1.1) $_\lambda$  satisfying  $\lim_{|x| \rightarrow \infty} u(x) = c$ .*

*Proof* It is easy to check that  $u$  is a solution of (1.1) $_\lambda$ , with  $\lim_{|x| \rightarrow \infty} u(x) = c$  if and only if  $v = u - c$  is a solution of

$$\begin{aligned} -\Delta v &= \lambda g(x) \tilde{f}(v), & x \in \mathcal{R}^n \\ \lim_{|x| \rightarrow +\infty} v(x) &= 0. \end{aligned} \tag{3.2}$$

where  $\tilde{f}(v) = f(v + c)$ . Thus  $\tilde{f}(0) > 0$ ,  $\tilde{f}(1 - c) = 0$  and  $\tilde{f}(v) > 0$  for  $0 < v < 1 - c$ . We prove the existence of a solution of (3.2) by constructing appropriate sub and supersolutions. Clearly the function

$$\bar{v}(x) = \begin{cases} 1 - c, & \text{for } 0 \leq |x| \leq R_0 \\ (1 - c) \{R_0/|x|\}^{n-2}, & \text{otherwise} \end{cases}$$

defines a positive supersolution.

Suppose  $g = g_+ + g_-$  where  $g_+$  and  $g_-$  denote the positive and negative parts of  $g$ . Then the equation  $-\Delta \phi = g_-(x)$  has a negative solution

$$\phi(x) = c_n \int_{\mathcal{R}^n} \frac{g_-(y)}{|x - y|^{n-2}} dy,$$

such that  $\lim_{|x| \rightarrow +\infty} \phi(x) = 0$ . Since  $\phi(x)$  is bounded we can find  $\epsilon > 0$  such that  $\epsilon \phi(x) + c > 0$  and so  $\tilde{f}(\epsilon \phi(x)) > 0$ , for all  $x \in \mathcal{R}^n$ . Let  $\underline{v}(x) = \epsilon \phi(x)$ ; we shall show that  $\underline{v}(x)$  is a subsolution of (3.2) provided  $\lambda$  is sufficiently small.

If  $x \in \mathcal{R}^n$  and  $g(x) \geq 0$ , then

$$-\Delta \underline{v}(x) = \epsilon g_-(x) = 0 \leq \lambda g(x) \tilde{f}(\underline{v}(x)),$$

whereas if  $g(x) < 0$

$$-\Delta \underline{v}(x) = \epsilon g(x), \quad \text{and} \quad \lambda g(x) \tilde{f}(\underline{v}(x)) > \lambda \mu g(x),$$

where  $\mu$  is such that  $f(u) \leq \mu$  for all  $0 \leq u \leq 1$ . Thus  $\underline{v}$  is a subsolution provided that  $\epsilon g(x) < \lambda \mu g(x)$  whenever  $g(x) < 0$ , i.e., provided that  $\lambda < \epsilon/\mu$  and so the proof is complete.  $\diamond$

**Acknowledgments.** The authors would like to thank the British Council for supporting an exchange programme, in the course of which this work originated. The second of the authors is grateful to the Department of Mathematics of Heriot-Watt University for hospitality and his own Department for financial support during the preparation of this work.

## References

- [1] K. J. Brown, S. S. Lin, and A. Tertikas, *Existence and nonexistence of steady-state solutions for a selection-migration model in population genetics*, J. Math. Biol. 27 (1989), 91-104
- [2] K.J.Brown, and A.Tertikas, *On the bifurcation of radially symmetric steady-state solutions arising in population genetics*,SIAM Jour. on Math. Anal. 22 (1991), 400-413.
- [3] W. H. Fleming, *A selection-migration model in population genetics*, J. Math. Biol. 2 (1975), 219-233.
- [4] Y. Li, and W.-M. Ni, *On conformal scalar curvature in equations in  $\mathcal{R}^n$* , Duke Math. J. 57 (1988), 895-924.
- [5] M. H. Protter, and H. F. Weinberger, "Maximum Principles in Differential Equations", Springer Verlag, Berlin Heidelberg, New York, 1967.
- [6] A. Tertikas, *Global bifurcation of positive solutions in  $\mathcal{R}^n$*  , in: Nonlinear Diffusion Equations and their Equilibrium States, in: Progress in Nonlinear Differential Equations and their Applications, Vol. 7, Birkhäuser Verlag, 1992.
- [7] A. Tertikas, *Uniqueness and nonuniqueness of positive solutions for a semilinear elliptic equation in  $\mathcal{R}^n$* , to appear in: Differential and Integral Equations.